

PLEQUE

—

PLasma EQUilibrium Enjoyment in Python

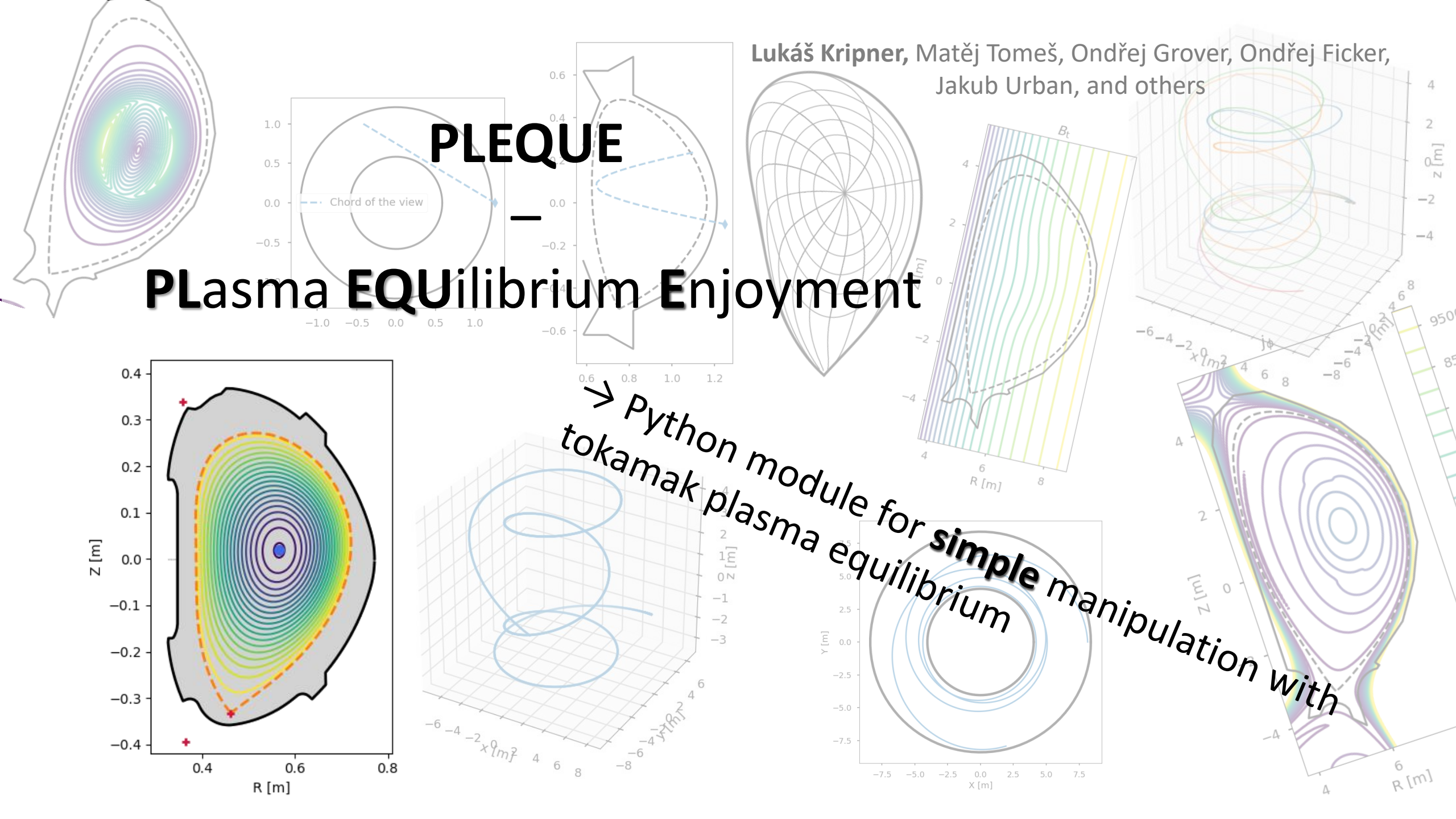
Lukáš Kripner^{1), 2)}, Matěj Tomeš^{1), 2)}, Ondřej Grover²⁾,
Ondřej Ficker²⁾, Jakub Urban²⁾, and others

*Katedra fyzik povrchů a plazmatu
Matematickofyzikální fakulta, Univerzita Karlova,
Praha*

*COMPASS tokamak
Institute of Plasma Physics of the CAS, Prague*

Lukáš Kripner, Matěj Tomeš, Ondřej Grover, Ondřej Ficker,
Jakub Urban, and others

PLEQUE — PLasma EQUilibrium Enjoyment



→ Python module for **simple** manipulation with
tokamak plasma equilibrium

$$\mathbf{J} \times \mathbf{B} = \nabla P$$

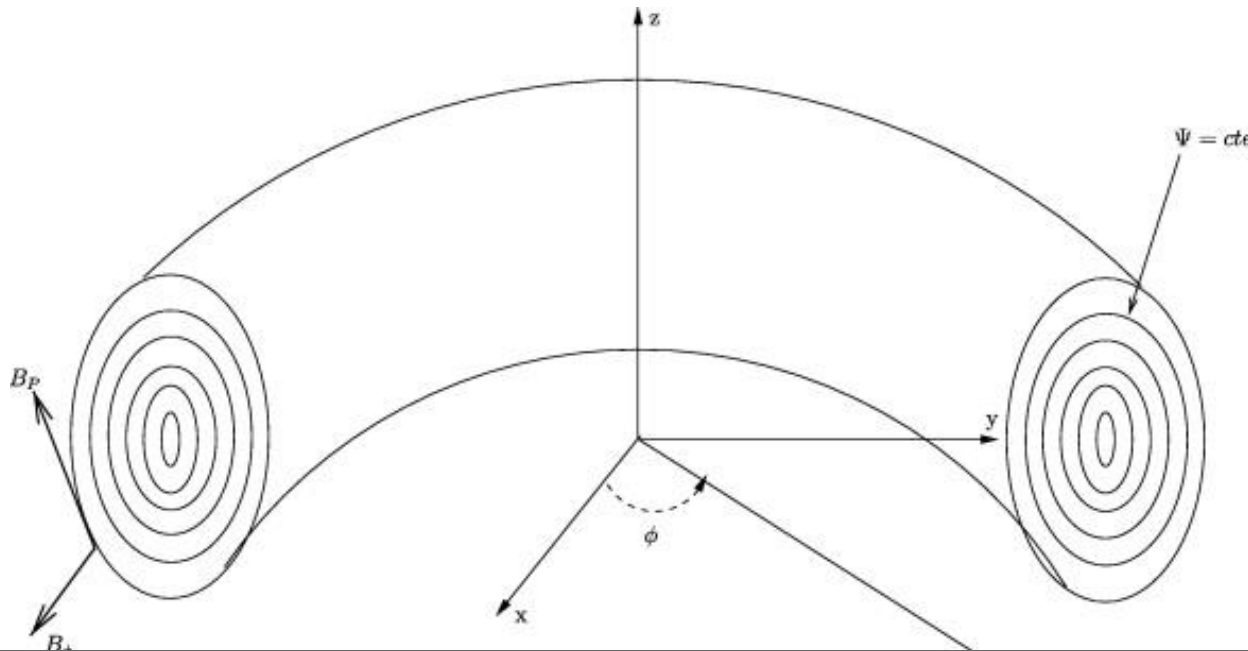
- The equilibrium of a magnetically confined plasma is defined by the magnetohydrodynamic (MHD) equations.
- Equilibrium requires external poloidal magnetic field.
- For stationary conditions (compared to the Alfvén time scale) and the axial symmetry, the Grad-Shafranov equation can be derived:

Grad-Shafranov equation:

$$\Delta^* \psi = -\mu_0 R^2 \frac{dp}{d\psi} - \frac{f df}{d\psi}$$

$$\Delta^* = R \frac{\partial}{\partial R} \left(\frac{1}{R} \frac{\partial}{\partial R} \right) + \frac{\partial^2}{\partial Z^2}$$

ψ = poloidal magnetic flux
 p = plasma pressure
 $f = RB_\phi$



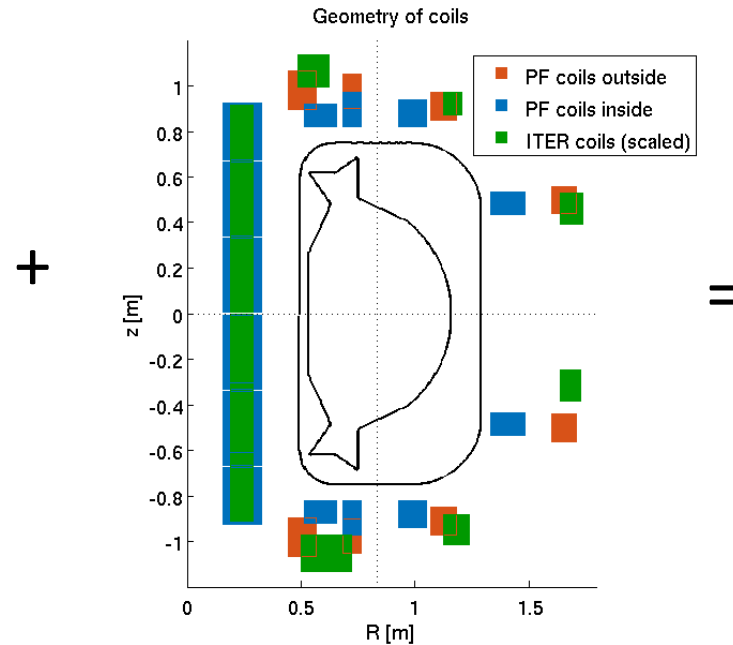
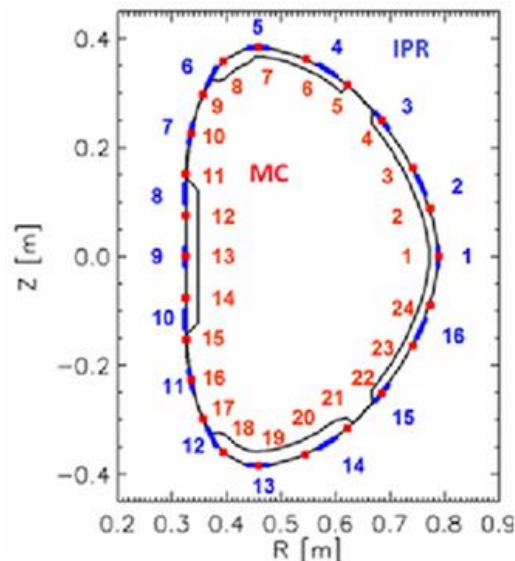
- **Fix/free boundary codes (CHEESE, HELENA, FREEBIE, FIESTA, etc.)**

$$\Delta^* \psi = -\mu_0 R^2 \frac{dp}{d\psi} - \frac{f df}{d\psi}$$

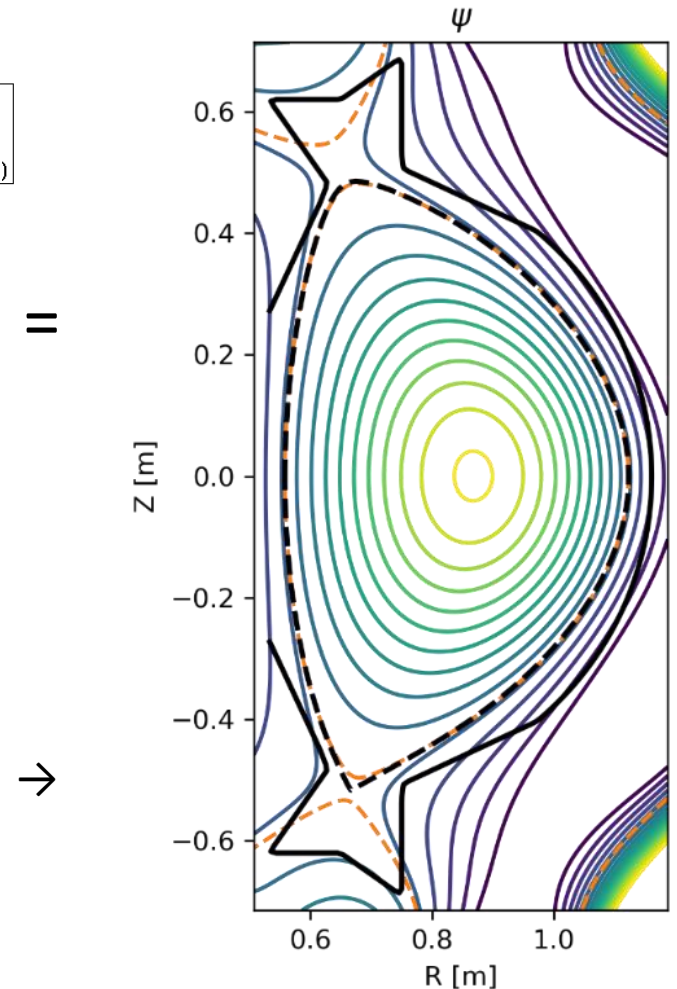
$$\Delta^* = R \frac{\partial}{\partial R} \left(\frac{1}{R} \frac{\partial}{\partial R} \right) + \frac{\partial^2}{\partial Z^2}$$

- Coil currents
- Current profile
- Pressure profile

- **Equilibrium codes for experiment (EFIT, ..)**



- Guessed profiles
- Fitting measured coils
- Fitting measured plasma current
- Fitting other diagnostics



$$\begin{array}{l}
 \psi(R, Z) \\
 p(\psi) \\
 f(\psi)
 \end{array}
 \left\{ \begin{array}{l}
 \mathbf{B} = (B_R, B_Z, B_\phi) \quad B_R = -\frac{1}{R} \frac{\partial \psi}{\partial Z} \quad B_Z = \frac{1}{R} \frac{\partial \psi}{\partial R} \\
 j_\theta \\
 j_\phi \\
 V_{\text{surf}} \\
 p(R, Z) \\
 q \\
 A_{\text{surf}} \\
 f(R, Z) \\
 I_{\text{plasma}}
 \end{array} \right.$$

$f = RB_\phi$

$j_\phi = -(Rp' + \frac{1}{\mu_0} f f')$

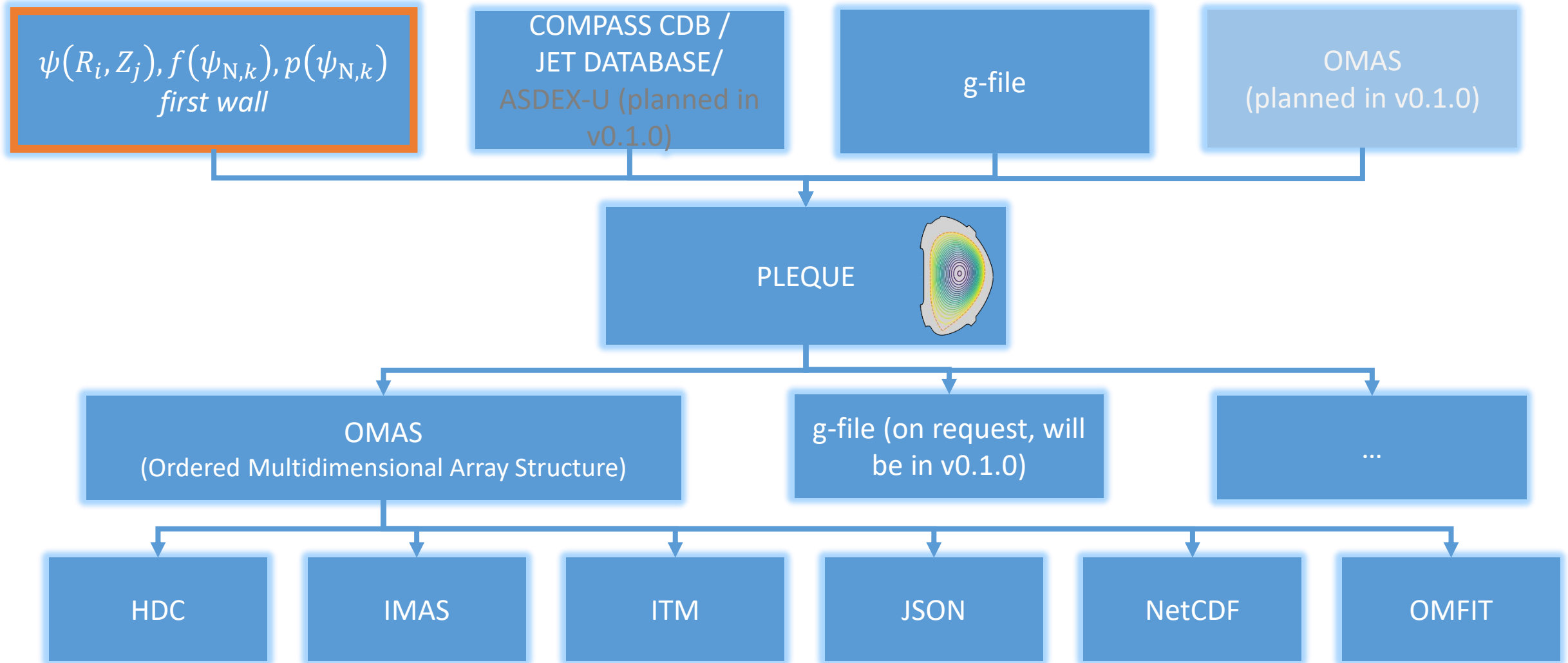
$j_\theta = \frac{1}{R\mu_0} f' |\nabla \psi|$

$B_\phi = Rf$

$q = \frac{d\Phi}{d\psi} = \frac{gV'}{(2\pi)^2} \langle R^{-2} \rangle$

$\langle a \rangle = \frac{2\pi}{V'} \oint a \frac{R d\ell}{|\nabla \psi|}$

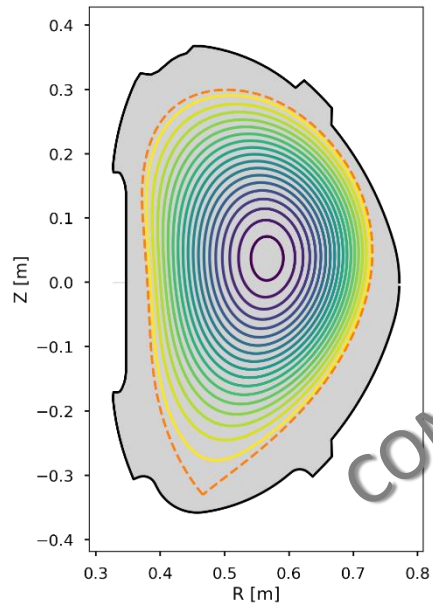
$I_p = \frac{V'}{2\pi\mu_0} \left\langle \frac{|\nabla \psi|^2}{R^2} \right\rangle$



CDB

```
# CDB
from pleque.io import compass
# shot, time
eq = compass.cdb(17829, 1100)

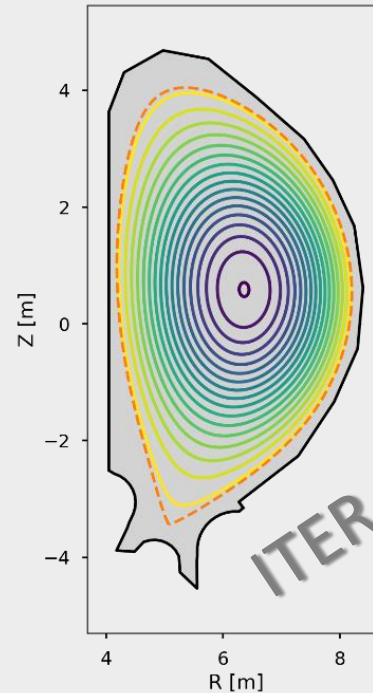
# from COMPASS HDF5:
eq = compass.read_efithdf5(
    '/compass/CC18_CDB_data/17829/EFITXX/EFITXX.1.h5'
    , time=1100)
```



g-file

```
from pleque.io.readers import read_geqdsk

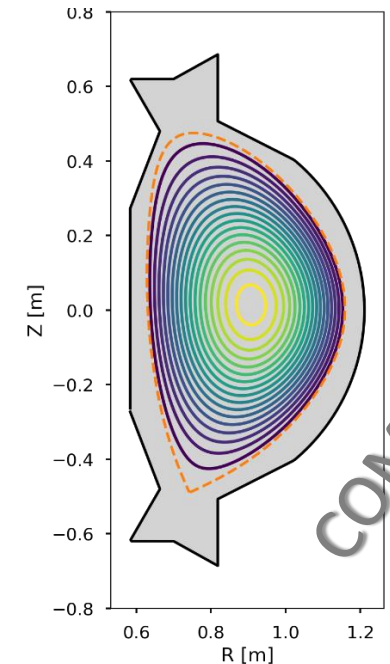
eq = read_geqdsk(
    '/path_to_your_eqdsk_file/shot.eqdsk')
```



Fiesta g-file

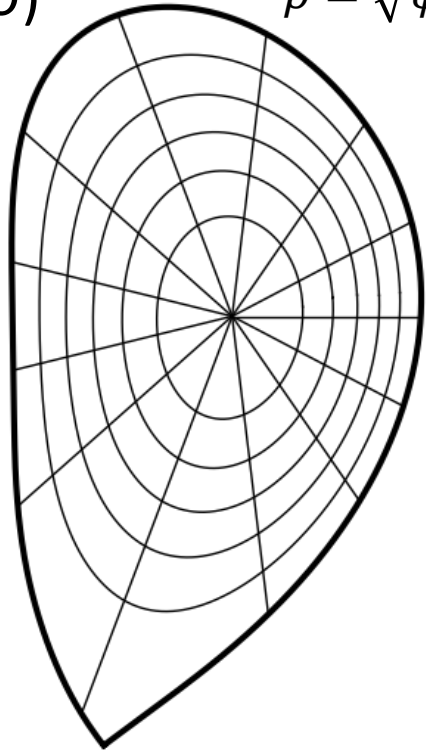
```
from pleque.io import compass

fiesta_file = '/compass/Shared/Common/COMPASS-
UPGRADE/RP1 ,\\
    'Design/Equilibria/v3.1/baseline_eqdsk'
eq =
    compass.read_fiesta_equilibrium(
        fiesta_file)
```



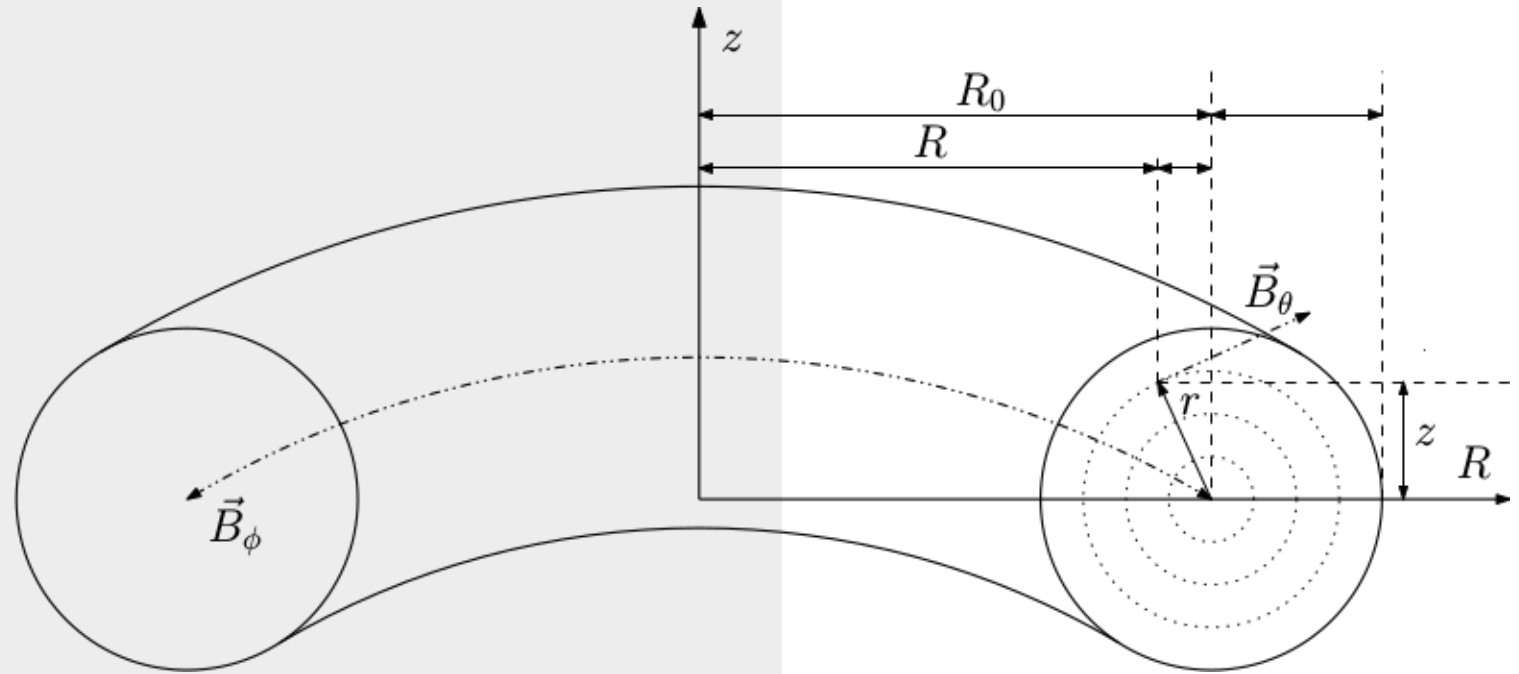
1D

- (ψ)
 - (ψ_N)
 - (σ)
- $$\psi_N = \frac{\psi - \psi_{ax}}{\psi_{ax} - \psi_{lcsf}}$$
- $$\rho = \sqrt{\psi_N}$$



2D

- (R, Z) – tokamak axis
- (r, ϑ) – magnetic axis



3D

- (R, Z, ϕ)
- (X, Y, Z)


```
# most of the functions has a special head:
```

```
def coordinates(self, *coordinates, coord_type=None, grid=False, **coords):
```

```
# 2d
```

```
coord = eq.coordinates(R=1, Z=2) # one point
```

```
coord = eq.coordinates([1, 2, 3], [3, 5, 6]) # implicitly (R, Z)
```

```
coord = eq.coordinates(R=[1, 2, 3], Z=[3, 5, 6]) # explicitly define the type
```

```
coord = eq.coordinates(([1, 3], [2, 5], [3, 6])) # as set of points
```

```
coord = eq.coordinates(r=[0.2, 0.3, 0.3, 0.2], theta=[0, pi/2, pi, 3/2*pi])
```

```
# 1d
```

```
coord = eq.coordinates(psi=[0.4, 0.35, 0.3, 0.2, 0.15])
```

```
coord = eq.coordinates(psi_n=linspace(0, 1, 10))
```

```
# 3d case
```

```
coord = eq.coordinates(x=linspace(1, 5, 11), y=zeros(11), z=zeros(11))
```

Coordinates

Accepted coordinates types

1D - coordinates

Coordinate	Code	Note
ψ_N	<code>psi_n</code>	Default 1D coordinate
ψ	<code>psi</code>	
ρ	<code>rho</code>	$\rho = \sqrt{\psi_n}$

2D - coordintares

Coordinate	Code	Note
(R, Z)	<code>R, Z</code>	Default 2D coordinate
(r, θ)	<code>r, theta</code>	Polar coordinates with respect to magnetic axis

3D - coordinates

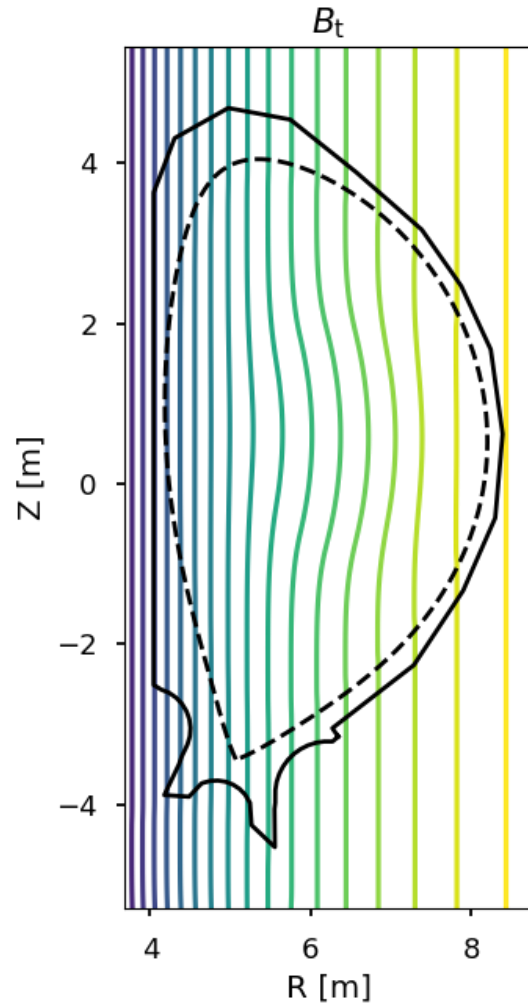
Coordinate	Code	Note
(R, Z, ϕ)	<code>R, Z, phi</code>	Default 3D coordinate
(X, Y, Z)	<code>X, Y, Z</code>	

```
coord = eq.coordinates(x=linspace(1, 5, 11), y=zeros(11), z=zeros(11)) # define 3D Coordinate object
```

```
r_mid = coord.r_mid    r = coord.r
R = coord.R            psi = coord.psi
X = coords.X           ...
```

```
coord = eq.coordinates(
    linspace(4, 8.2),
    linspace(-5, 5),
    grid=True)
```

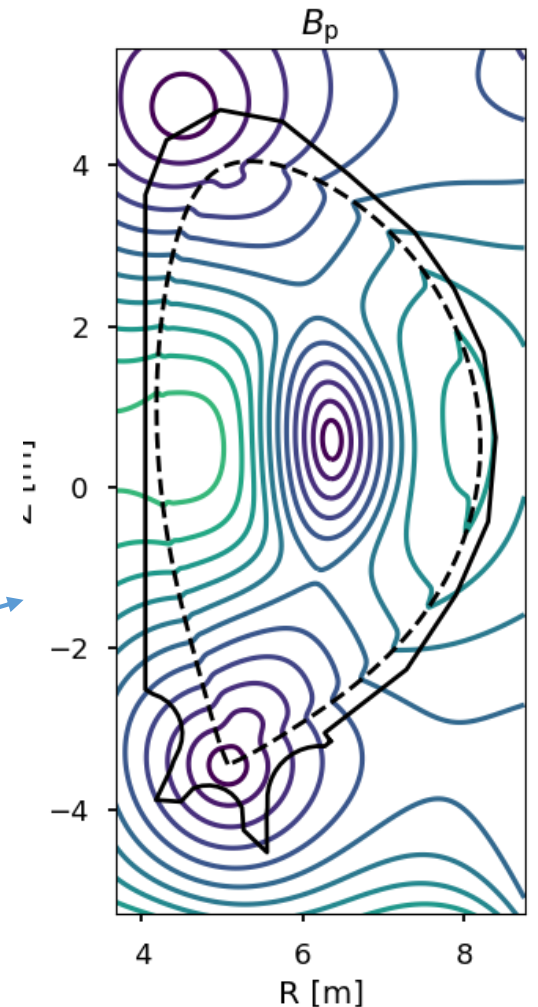
```
# this return 2D array
Bt = eq.B_tor(coord)
```

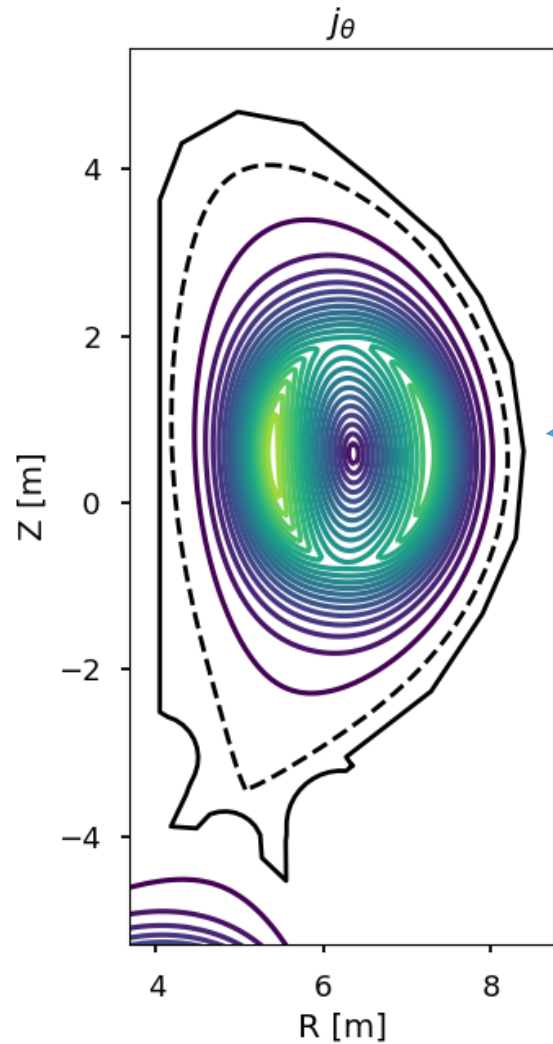


$$B_\phi = \frac{f}{R}$$

```
Bp = eq.B_pol(linspace(4, 8.2),
    linspace(-5, 5),
    grid=True)
```

$$\frac{1}{R} |\nabla \psi|$$

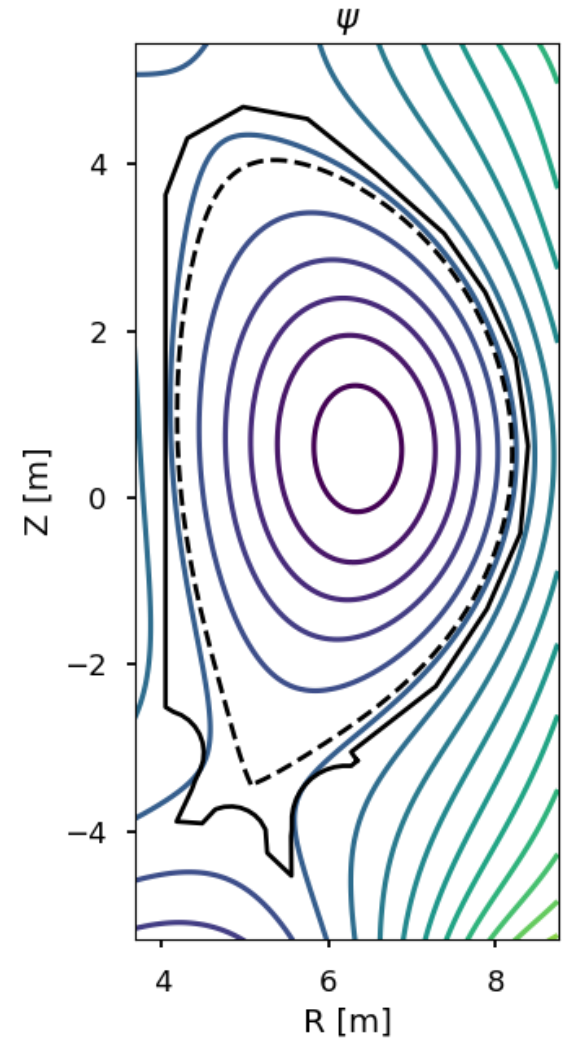




```
# default Coordinates grid
grid = eq.grid()
j_pol = eq.j_pol(grid)
```

$$j_{\theta} = \frac{1}{R\mu_0} f' |\nabla\psi|$$

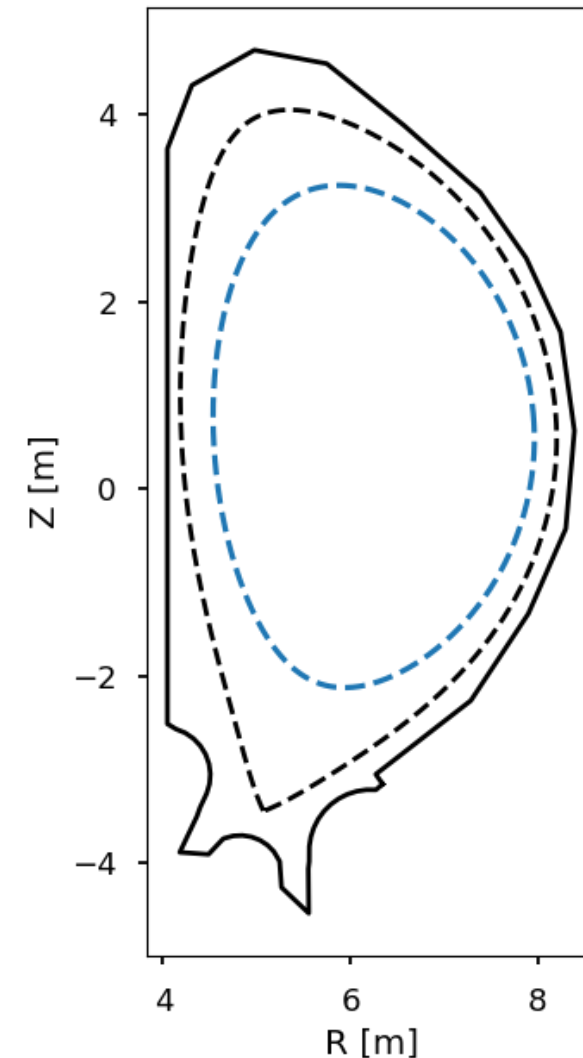
```
psi = grid.psi
```

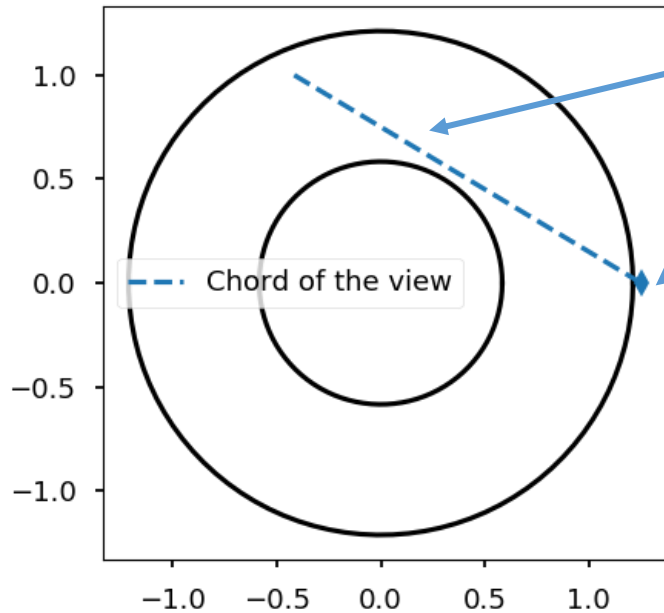


```
surf = eq.flux_surface(psi_n=0.8) [0]
```

```
dict(q           = surf.eval_q,  
     length      = surf.length,  
     area        = surf.area,  
     volume      = surf.volume,  
     current     = surf.tor_current/1e6)
```

```
{'q': array([-1.99901063]),  
 'length': 13.973753170736375,  
 'area': 14.311638142524348,  
 'volume': 554.01117642953955,  
 'current': 13.000279670184989}
```



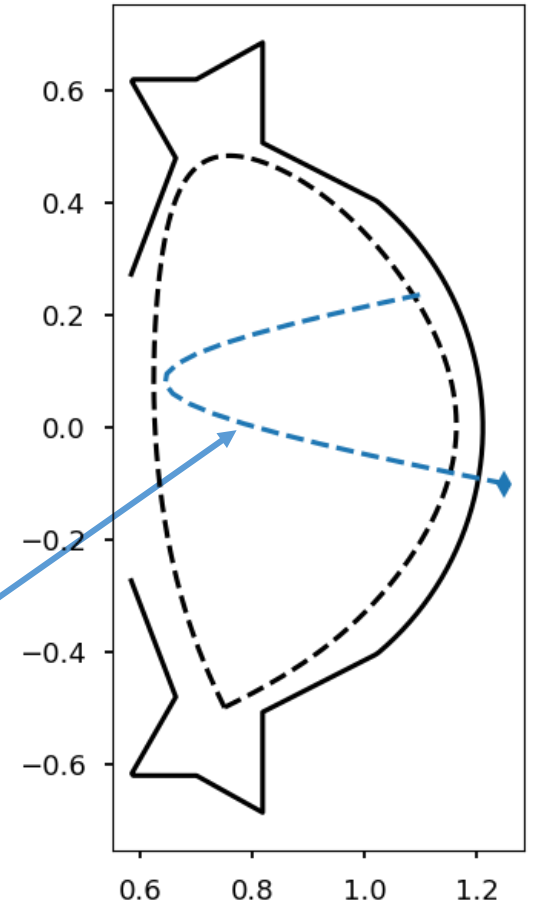


```
#          ( x,   y,   z)
direction = array((-1, 0.6, 0.2))
direction /= norm(direction)

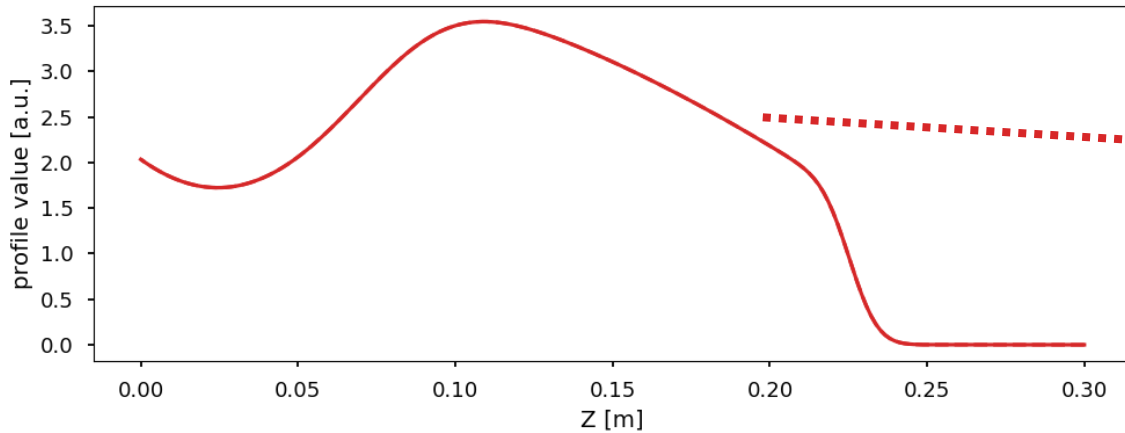
position = array((1.25, 0, -0.1))

camera_view = eq.coordinates(
    position+direction[newaxis,:]*
    linspace(0, 2.0, 20)[: , newaxis],
    coord_type=('X', 'Y', 'Z'))

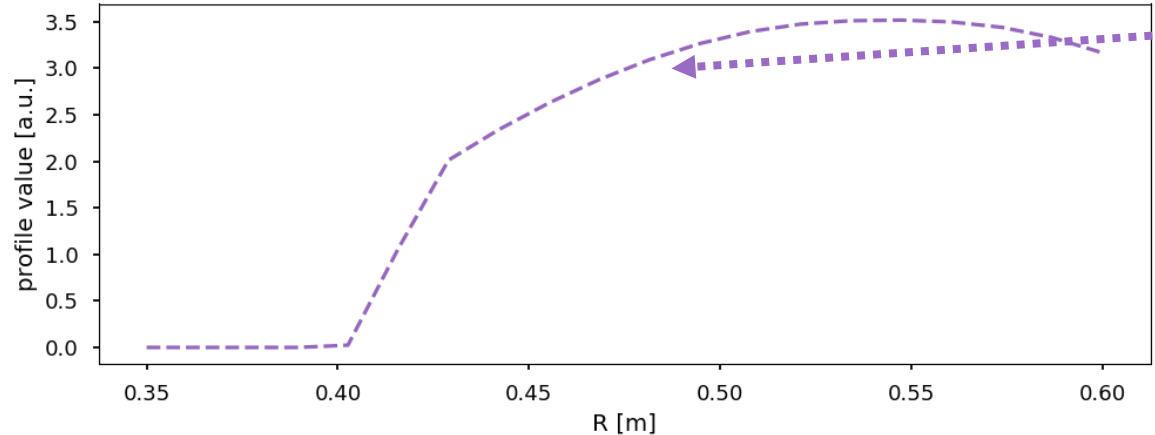
plot(camera_view.X, camera_view.Y, 'x--',
      label='Chord of the view')
...
plot(camera_view.R, camera_view.Z, 'x--')
```



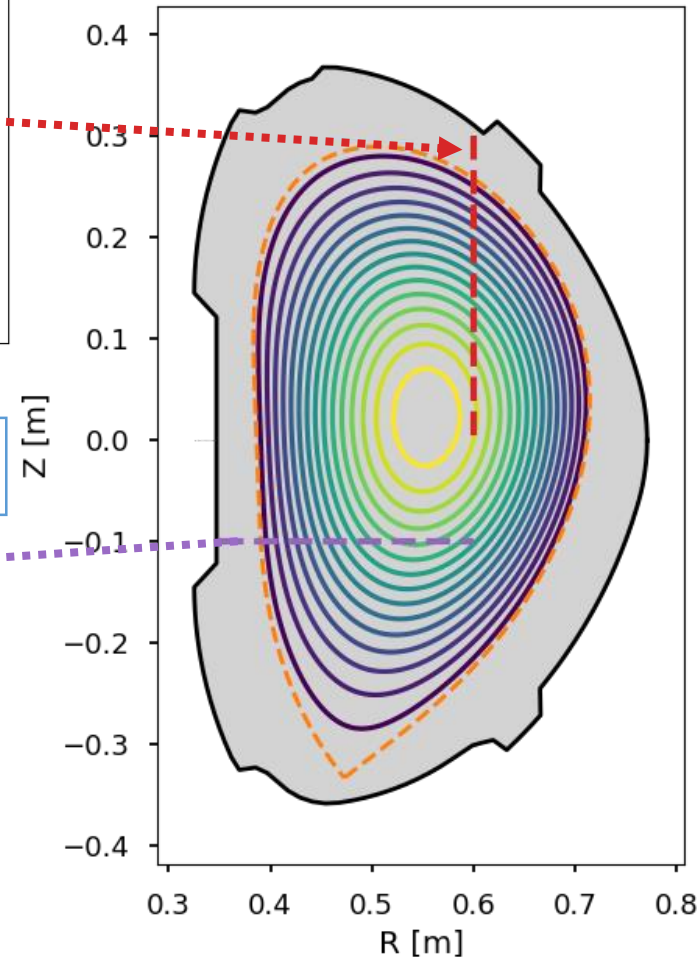
Side note: there is module `pleque.spatran` which can handle work with diagnostics much better (**responsible person: Matej**, to be presented)



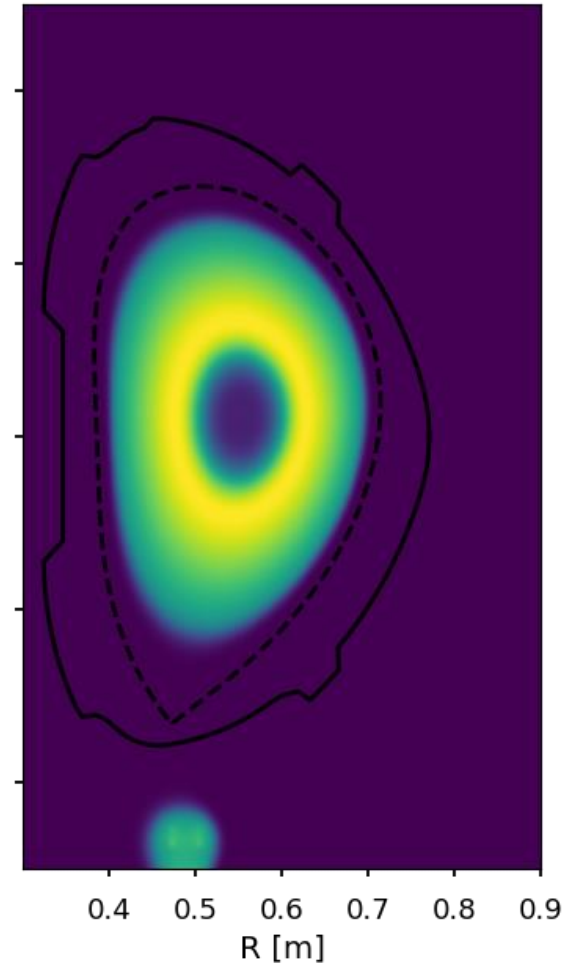
```
eq.fluxfuncs.add_flux_func('test_prof',  
    chord_prof, chord1)
```

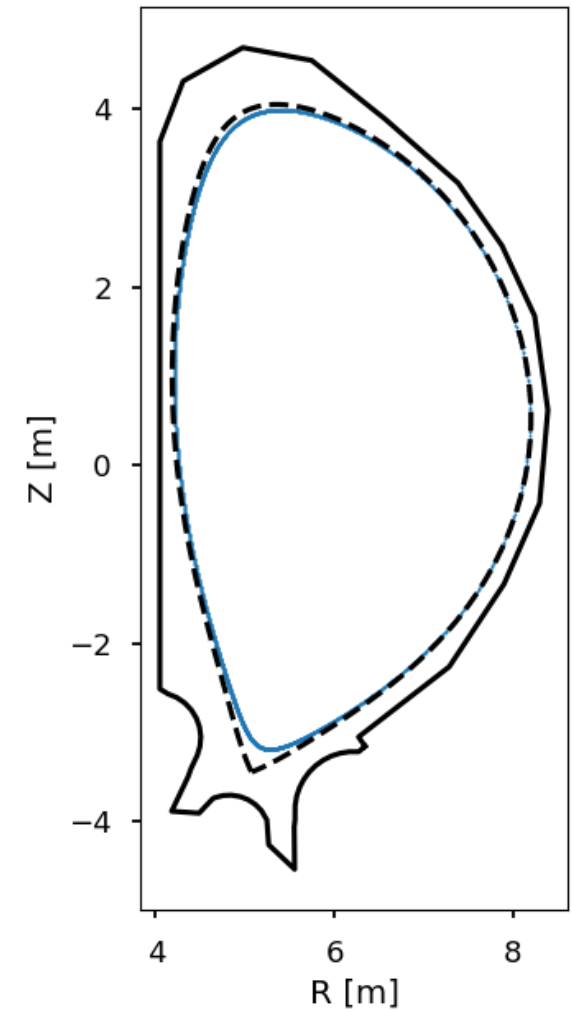
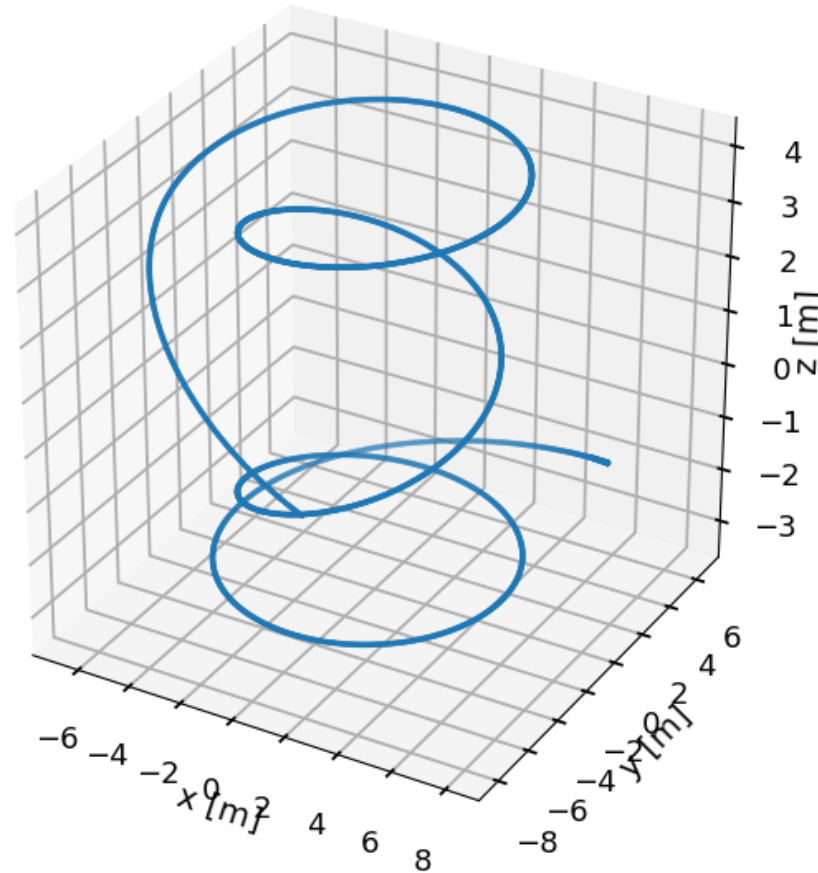
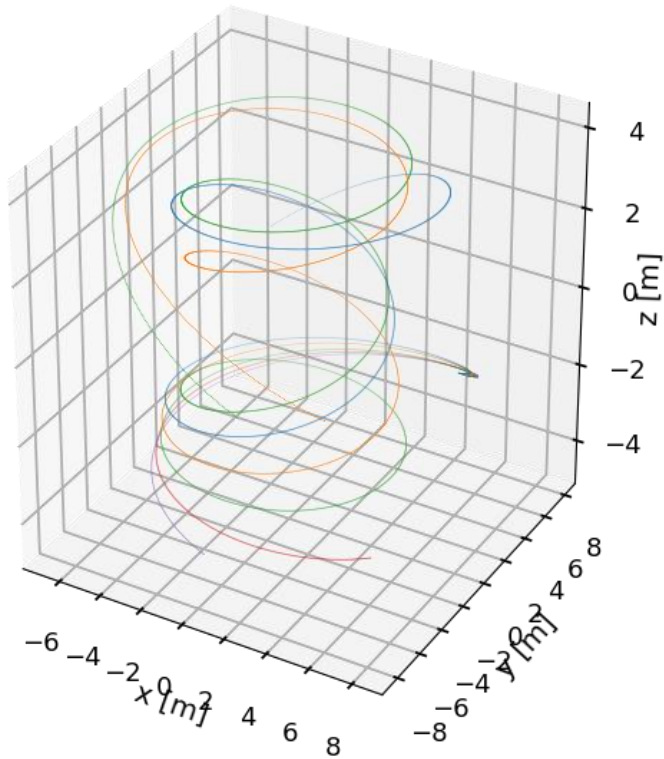


```
plt.plot(chord2.R, eq.fluxfuncs.test_prof(chord2),  
    '--', color='C4')
```



```
grid = eq.grid()  
ax.pcolormesh(grid.R, grid.Z, eq.fluxfuncs.test_prof(grid))
```

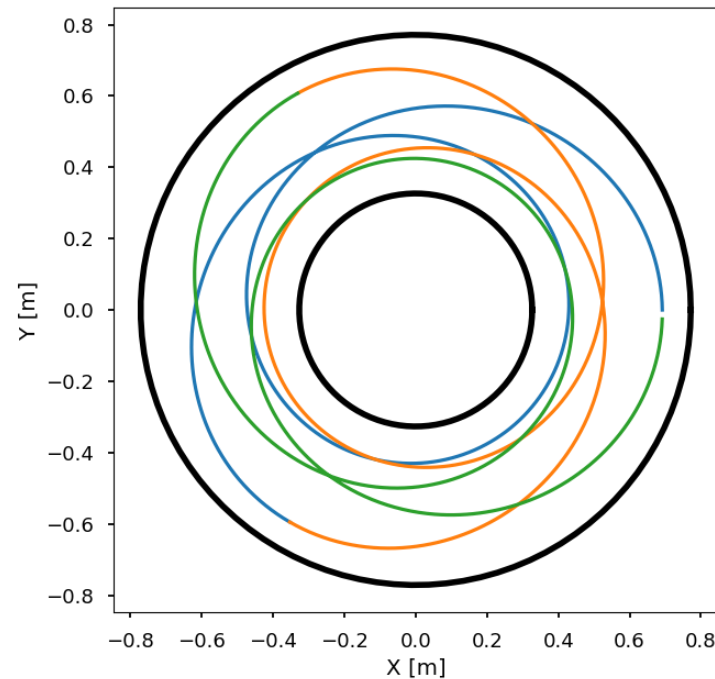
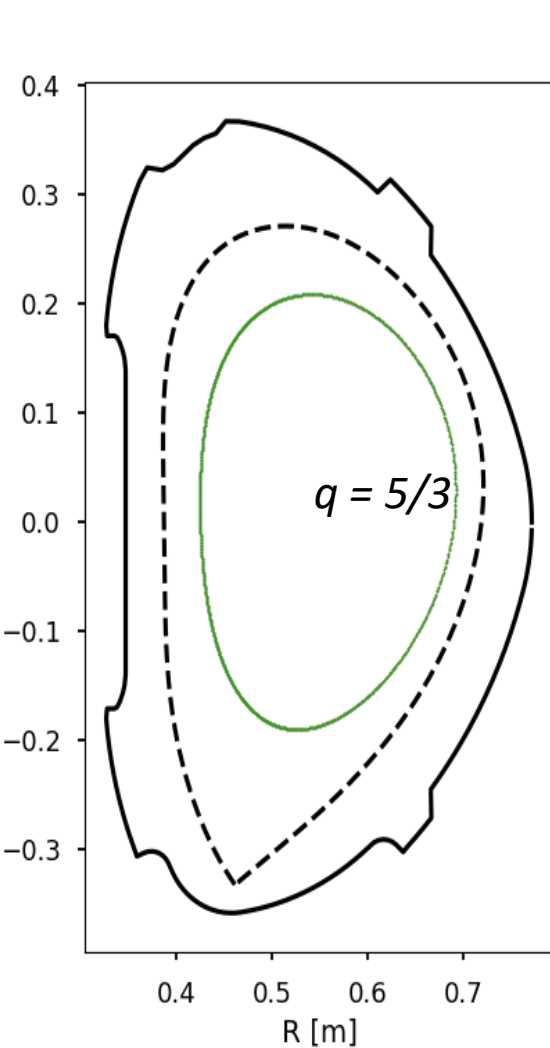




```
rs = np.linspace(8, 8.3, N)
zs = np.zeros_like(rs)

traces = eq.trace_field_line(R=rs, Z=zs)

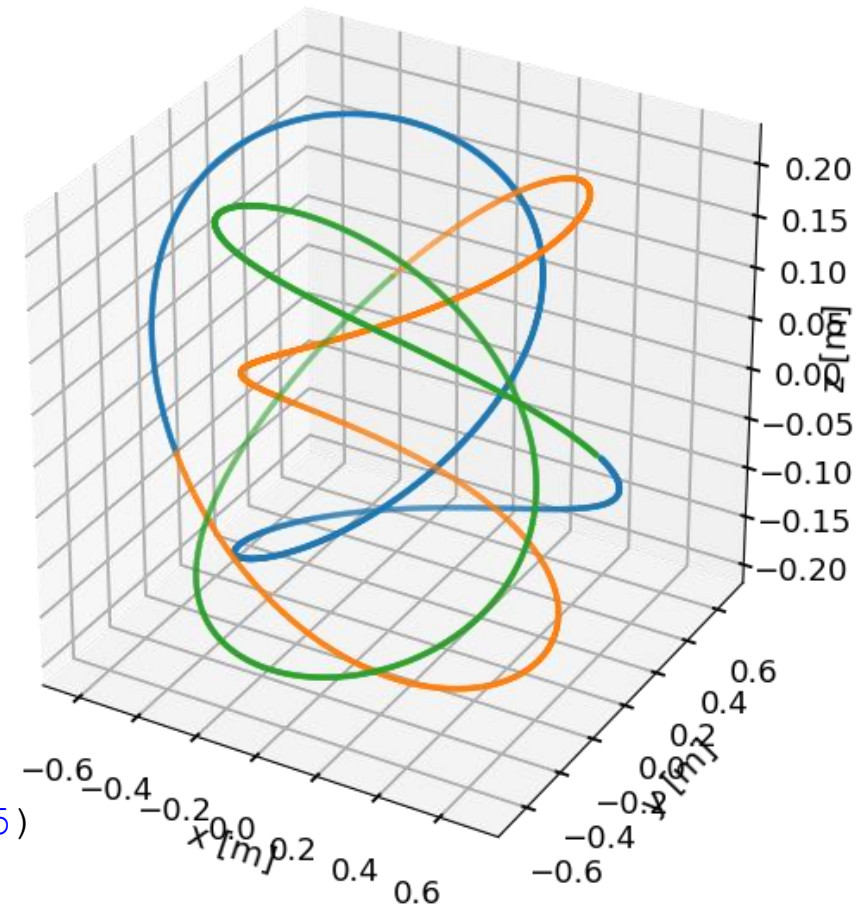
for fl in traces:
    scatter(fl.X, fl.Y, fl.Z, s=0.3, marker='.')
```

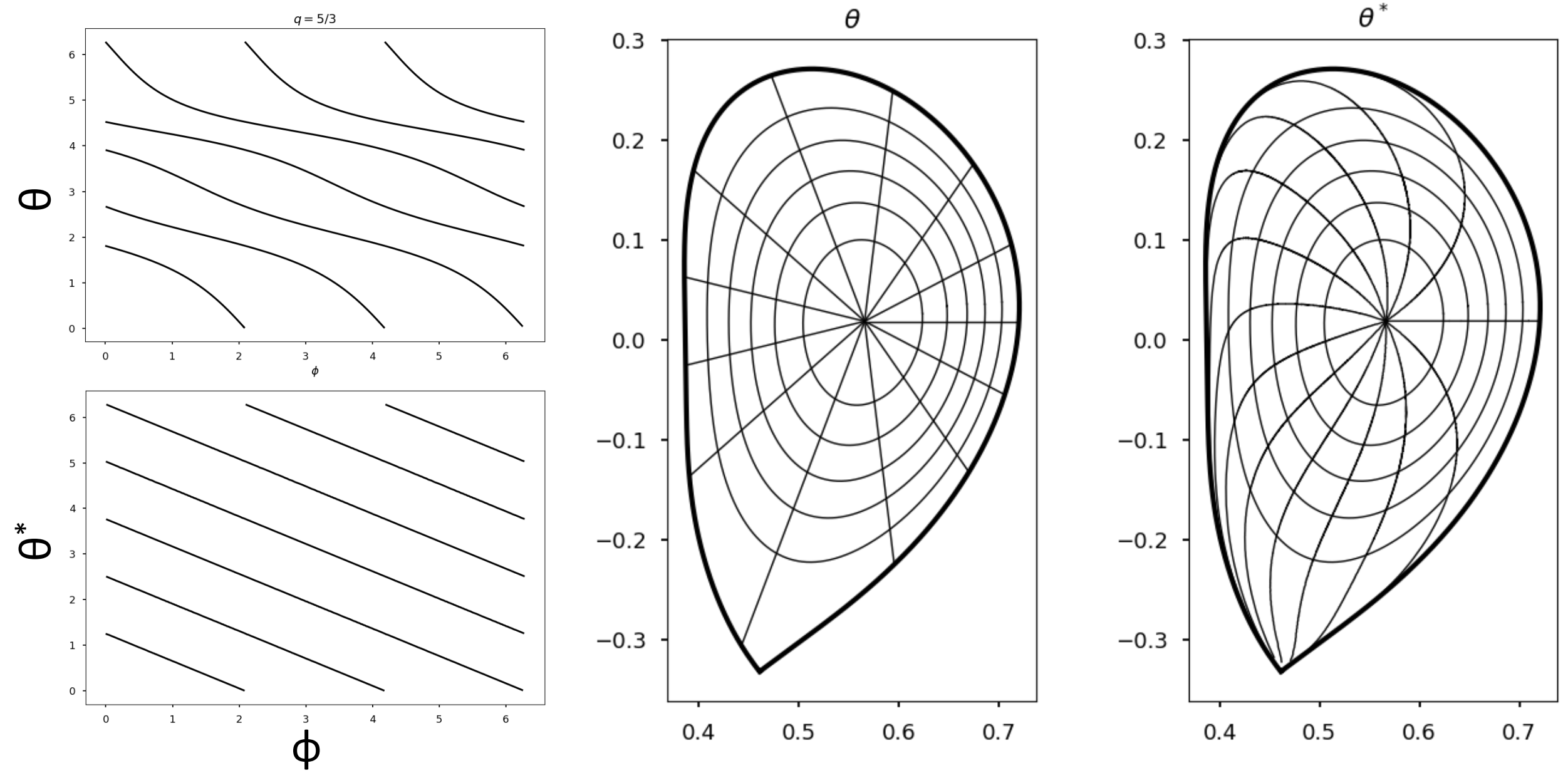


```
# brentq = scipy minimization function
from scipy.optimize import brentq
psi_onq = brentq(lambda psi_n:
    np.abs(eq.q(psi_n)) - 5/3, 0, 0.95)
```

```
surf = eq._flux_surface(psi_n = psi_onq)[0]
```

```
theta_star = surf.straight_fieldline_theta
```





<https://github.com/kripnerl/pleque>

<https://repo.tok.ipp.cas.cz/kripnerl/pleque>

pleque

Plaque - Plasma EQUilibrium Enjoyment module [pleig]

Python module for the simple manipulation with the tokamak plasma equilibrium. For more information see the documentation at <https://pleque.readthedocs.io>.

Getting Started

Plaque

Search docs

CONTENTS:

- Coordinates
- Examples
- API Reference

Welcome to Plaque's documentation!

Code home: <https://github.com/kripnerl/pleque/>

Contents:

- Coordinates
- Examples

API Reference

- API Reference

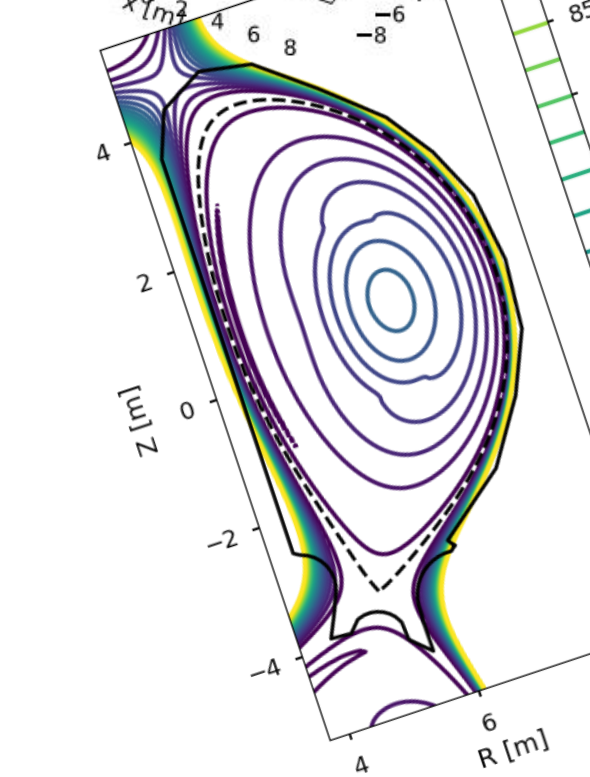
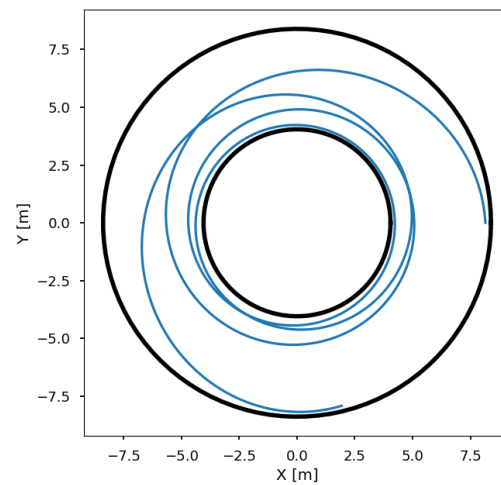
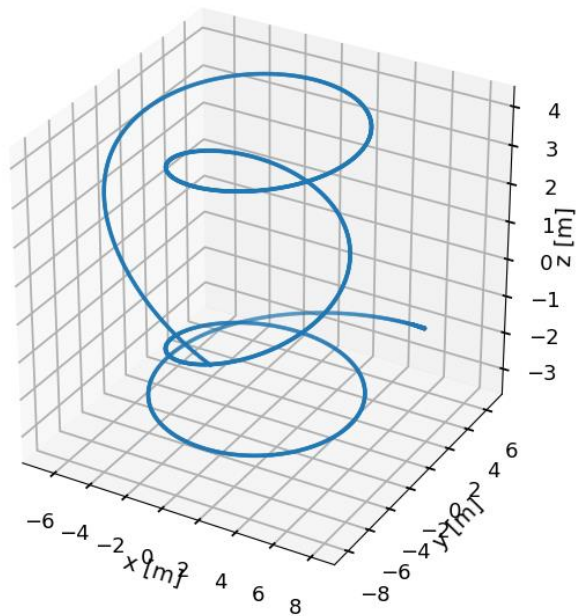
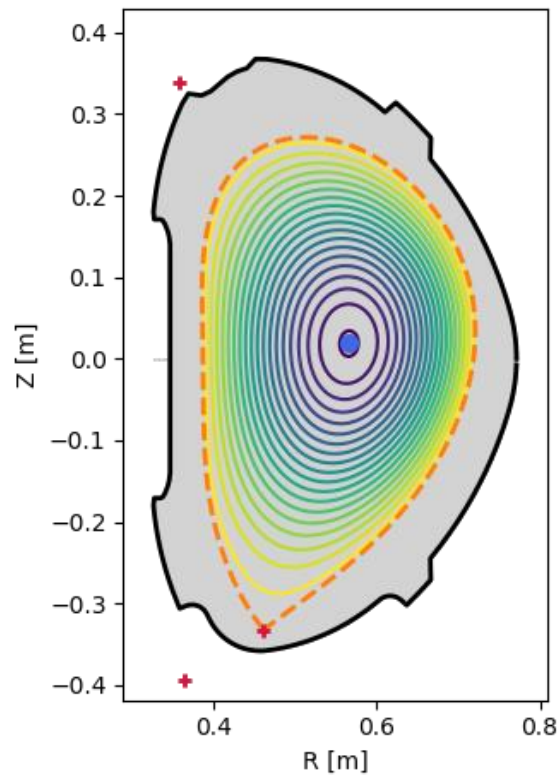
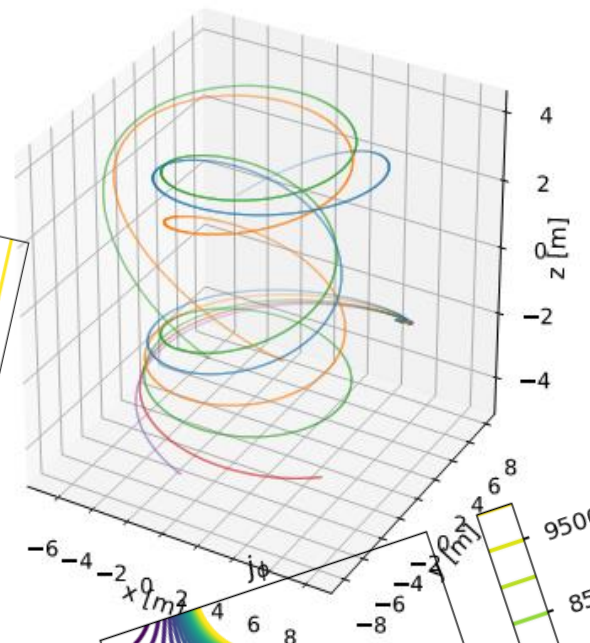
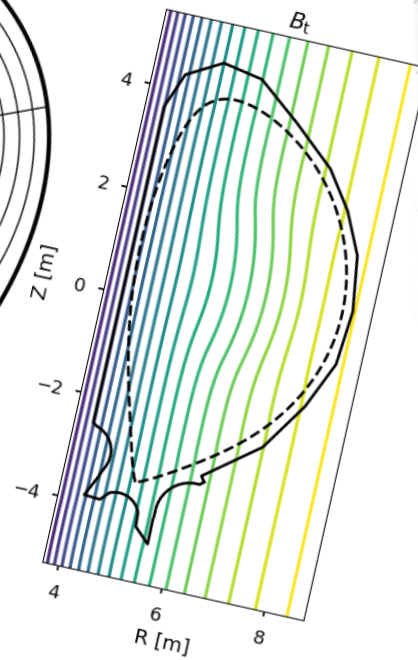
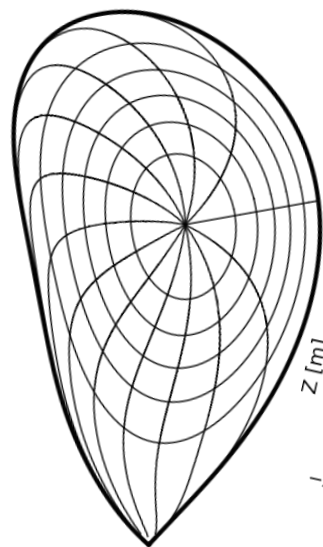
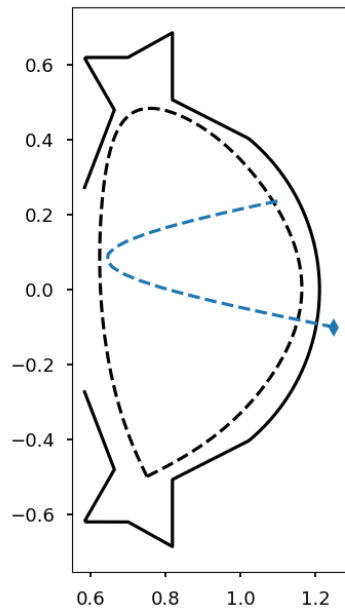
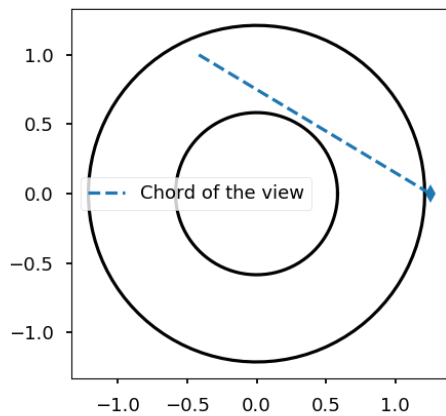
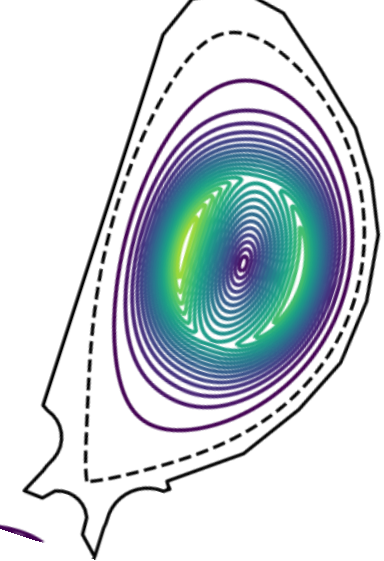
Indices and tables

- Index
- Module Index
- Search Page

© Copyright 2018, Lukas Kripner Revision b f3035b3.
Built with [Sphinx](#) using a [theme](#) provided by [Read the Docs](#).

[Next](#)

<https://pleque.readthedocs.io>



- Questions?**
- Create an issue on [gitlab/github](https://gitlab.com/ipp-cas/cas).
 - To shy for that? Write me email to kripner@ipp.cas.cz